Sriram Krishna

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Education ____

Carnegie Mellon University

MASTER OF SCIENCE IN ROBOTICS - GPA: 4.17/4.0

PES University

BACHELOR OF TECHNOLOGY IN COMPUTER SCIENCE AND ENGINEERING - OVERALL GPA: 8.99/10.0 || MAJOR GPA: 9.17/10.0

Experience

Carnegie Mellon University - Robotics Institute

GRADUATE RESEARCH ASSISTANT

- Advisor: David Held
- Currently working on learning 3D Goal Generation from large-scale human / robot data, towards guiding generalist robot manipulation policies.

Samsung Research

SOFTWARE ENGINEER - COMPUTER VISION

- AR Vision Lab Depth Estimation and 3D Scene Reconstruction Development of Spatial Understanding solutions
- Research and Development on depth estimation by leveraging a range of machine learning techniques such as self-supervised learning and knowledge distillation. Optimised models for real-time on-device inference and integrated depth subsystems into 3D Reconstruction pipeline.
- Designed and developed DeepSmooth, a model which achieved SOTA results for temporal consistency in depth completion. Paper presented at the VOCVALC workshop at CVPR 2023.
- Proposed the design and led implementation for a tool to generate ground truth depth / segmentation for an arbitrary camera system using a laser scanner & motion capture.
- Tech Stack: C++, PyTorch, CMake, ONNX

MIDAS-IIIT Delhi

Research Assistant - Part Time

- Improved reliability of Automated Scoring systems by bringing humans into the loop. Presented at EAAI 2022, organized jointly with AAAI-22
- Evaluated viability of Topological Data Analysis (TDA) for modeling the coherence of natural language text. Accepted in The Tiny Papers Track at ICLR 2024.

Nextuple Inc.

SOFTWARE ENGINEER

• Built Nextuple's Machine Learning Platform. Integrated the platform into existing infrastructure following best practices (logging, visualization, etc.) Tech Stack: Azure, Kubernetes, Kubeflow

SOFTWARE ENGINEER - INTERN

• Developed a simulation demonstrating a new sourcing model, showing 20% reduction in shipping costs and 20-50% reduction in the number of shipments. Designed and developed the simulation flow and core logic in a modular architecture.

OffNote Labs

DEEP | FARNING INTERN

• Developed GESTOP, an application for customizable gesture control of computer systems. The application provides an interface to communicate with a computer through hand gestures. Custom gestures to be recognized can be added to extend the application. Designed, developed and extensively documented the entire application.

Publications

- Samyak Jain, Rishi Singhal, Sriram Krishna, Yaman Kumar Singla, and Rajiv Ratn Shah. Beyond Words: A Topological Exploration of Coherence in Text Documents. In The Second Tiny Papers Track at ICLR, 2024.
- Sriram Krishna and Basavaraja Shanthappa Vandrotti. DeepSmooth: Efficient and Smooth Depth Completion. In Proceedings of the IEEE/CVF Conference on Computer Vision and Pattern Recognition - VOCVALC Workshop, pages 3357-3366, 2023.
- Yaman Kumar Singla*, Sriram Krishna*, Rajiv Ratn Shah, and Changyou Chen. Using sampling to estimate and improve performance of automated scoring systems with guarantees. In Proceedings of the AAAI Conference on Artificial Intelligence - Educational Advances in Artificial Intelligence, 2022.

Aug 2024 - Aug 2026 (Expected)

Bengaluru, India Aug 2017 - May 2021

Pittsburgh, PA

Bengaluru, India

Jul. 2021 - Dec. 2021

Jan 2021 - July 2021

Bengaluru, India

May. 2020 - Sep. 2020

Pittsburgh, PA Aug. 2024 - Present

Dec. 2021 - Apr. 2024

New Delhi, India Jun. 2021 - Jul. 2023

- Sriram Krishna and Nishant Sinha. Gestop: Customizable Gesture Control of Computer Systems. In 8th ACM IKDD CODS and 26th COMAD, pages 405–409. ACM, 2021.
- Sriram Krishna, Siddarth Vinay, and KS Srinivas. Searching a Raw Video Database using Natural Language Queries. In 2021 International Conference on Advances in Electrical, Computing, Communication and Sustainable Technologies (ICAECT), pages 1–6. IEEE, 2021.
- Sriram Krishna and Niharika Pentapati. Genetic Bi-objective Optimization Approach to Habitability Score. In *International Conference on Modeling, Machine Learning and Astronomy*, pages 144–157. Springer, 2019.

Projects

nanoraytracer

- A recursive raytracer written from scratch in C++
- Supports shadows, reflections, specular/diffuse lighting and sphere/triangle primitives. Implemented in a modular and extensible manner following C++ best practices.

FrLove - Could a Frenchman rapidly identify Lovecraft?

- Exploration of cross-domain few-shot learning from a multilingual perspective. Experiments to validate whether the "distance" between different language families can be quantified in terms of their few-shot performance.

YAG - Yet Another Google

- An implementation of a search engine in Python
- A search engine which can construct an inverted index on a corpus and then retrieve results for various types of queries. In addition to plain queries, it also supports phrase queries and wildcard queries.

Face Colorizer

• Developed and trained a CycleGAN using Tensorflow. The model was trained on the Labeled Faces in the Wild (LFW) dataset, and after training, could colorize black and white images of faces.

Skills ____

Programming Languages	Python, C++, C
Relevant Coursework	Data Structures & Algorithms, Computer Vision, Operating Systems, Human Computer Interaction,
	Machine Learning, Artificial Intelligence, Computer Graphics, Information Retrieval
Tools and Frameworks	PyTorch, OpenCV, Flask, Docker, CMake, Tensorflow, Kubernetes, Azure
Additional	Shell Scripting, Latex